HEF4015B

Dual 4-bit static shift register Rev. 8 — 21 November 2011

Product data sheet

1. **General description**

The HEF4015B is a dual edge-triggered 4-bit static shift register (serial-to-parallel converter). Each shift register has a serial data input (D), a clock input (CP), four fully buffered parallel outputs (Q0 to Q3) and an overriding asynchronous master reset input (MR). Information present on D is shifted to the first register position, and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. A HIGH on MR clears the register and forces Q0 to Q3 to LOW, independent of CP and D. The clock input's Schmitt trigger action makes the input highly tolerant of slower clock rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD}, V_{SS}, or another input.

Features and benefits 2.

- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from -40 °C to +85 °C.
- Complies with JEDEC standard JESD 13-B

3. **Applications**

- Serial-to-parallel converter
- **Buffer stores**
- General purpose register

4. Ordering information

Table 1. **Ordering information**

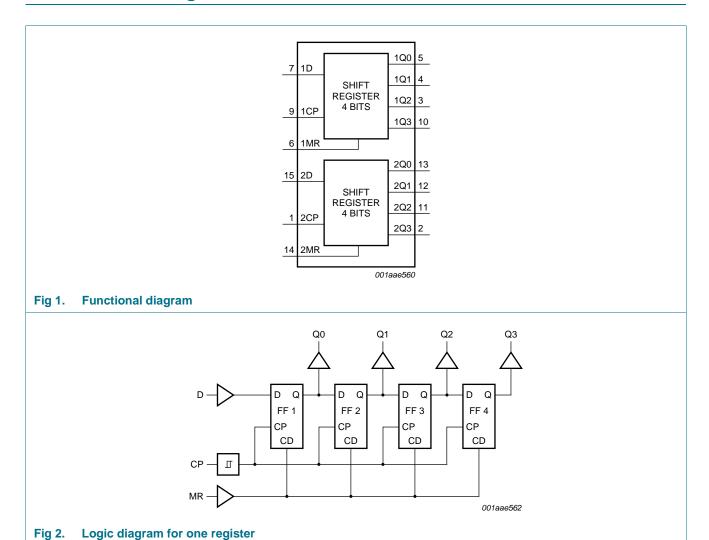
All types operate from $-40 \,^{\circ}\text{C}$ to $+85 \,^{\circ}\text{C}$.

Type number	Package		
	Name	Description	Version
HEF4015BP	DIP16	plastic dual in-line package; 16 leads (300 mil)	SOT38-4
HEF4015BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1



Dual 4-bit static shift register

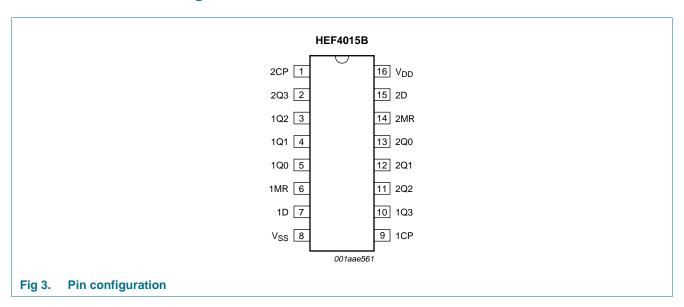
5. Functional diagram



Dual 4-bit static shift register

6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
1Q0 to 1Q3	5, 4, 3, 10	parallel output
2Q0 to 2Q3;	13, 12, 11, 2	parallel output
1MR, 2MR	6, 14	master reset input (active HIGH)
1D, 2D	7, 15	serial data input
V_{SS}	8	ground supply voltage
1CP, 2CP	9, 1	clock input (LOW-to-HIGH edge-triggered)
V_{DD}	16	supply voltage

7. Functional description

Table 3. Function table 11

number of clock	Input			Output				
pulse transitions	СР	D	MR	Q0	Q1	Q2	Q3	
1	\uparrow	D1	L	D1	Χ	X	X	
2	↑	D2	L	D2	D1	Χ	X	
3	↑	D3	L	D3	D2	D1	X	
4	↑	D4	L	D4	D3	D2	D1	
	\	Χ	L	no change	no change	no change	no change	
	X	X	Н	L	L	L	L	

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Dn = either HIGH or LOW;

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 $[\]uparrow$ = positive-going transition; \downarrow = negative-going transition.

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8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_I < -0.5 \text{ V or } V_I > V_{DD} + 0.5 \text{ V}$	-	±10	mA
V_{I}	input voltage		-0.5	$V_{DD} + 0.5$	V
I _{OK}	output clamping current	$V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I_{DD}	supply current		-	50	mA
T_{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+85	°C
P _{tot}	total power dissipation	$T_{amb} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}$			
		DIP16 package	<u>[1]</u> -	750	mW
		SO16 package	[2] -	500	mW
Р	power dissipation	per output	-	100	mW

^[1] For DIP16 package: P_{tot} derates linearly with 12 mW/K above 70 °C.

9. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V_{DD}	supply voltage		3	-	15	V
VI	input voltage		0	-	V_{DD}	V
T _{amb}	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	$V_{DD} = 5 V$	-	-	3.75	μs/V
		V _{DD} = 10 V	-	-	0.5	μs/V
		V _{DD} = 15 V	-	-	0.08	μs/V

^[2] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

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10. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	T _{amb} =	-40 °C	T _{amb} =	25 °C	T _{amb} = 85 °C		Unit
				Min	Max	Min	Max	Min	Max	
V_{IH}	HIGH-level input voltage	$ I_{O} < 1 \mu A$	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V_{IL}	LOW-level input voltage	$ I_{O} < 1 \mu A$	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level output voltage	$ I_O < 1 \mu A$	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V _{OL} L	LOW-level output voltage	$ I_O < 1 \mu A$	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level output current	$V_0 = 2.5 \text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	mΑ
		$V_0 = 4.6 \text{ V}$	5 V	-	-0.52	-	-0.44	-	-0.36	mΑ
		$V_0 = 9.5 V$	10 V	-	-1.3	-	-1.1	-	-0.9	mΑ
		$V_{O} = 13.5 \text{ V}$	15 V	-	-3.6	-	-3.0	-	-2.4	mΑ
I _{OL}	LOW-level output current	$V_0 = 0.4 \ V$	5 V	0.52	-	0.44	-	0.36	-	mΑ
		$V_0 = 0.5 \ V$	10 V	1.3	-	1.1	-	0.9	-	mΑ
		$V_0 = 1.5 \text{ V}$	15 V	3.6	-	3.0	-	2.4	-	mΑ
I _I	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μΑ
I _{DD}	supply current	$I_O = 0 A$	5 V	-	20	-	20	-	150	μΑ
			10 V	-	40	-	40	-	300	μΑ
			15 V	-	80	-	80	-	600	μΑ
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

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11. Dynamic characteristics

Table 7. Dynamic characteristics

 $V_{SS} = 0$ V; $C_L = 50$ pF; $T_{amb} = 25$ °C.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula[1]	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW	nCP to Qn;	5 V	103 ns + (0.55 ns/pF)C _L	-	130	260	ns
	propagation delay	see Figure 4	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		nMR to Qn;	5 V	78 ns + (0.55 ns/pF)C _L	-	105	210	ns
		see Figure 6	10 V	34 ns + (0.23 ns/pF)C _L	-	45	90	ns
			15 V	27 ns + (0.16 ns/pF)C _L	-	35	70	ns
t _{PLH}	LOW to HIGH	nCP to Qn	5 V	93 ns + (0.55 ns/pF)C _L	-	120	240	ns
	propagation delay	n delay see <u>Figure 4</u>	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
t _t	transition time	see Figure 4	5 V	10 ns + (1.00 ns/pF)C _L	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns
t _{su}	set-up time	nD to nCP;	5 V		+25	-15	-	ns
		see Figure 5	10 V		+25	-10	-	ns
			15 V		+20	-5	-	ns
t _h	hold time	nD to nCP; see <u>Figure 5</u>	5 V		40	20	-	ns
	noid time		10 V		20	10	-	ns
			15 V		15	8	-	ns
t _W	pulse width	nCP LOW;	5 V		60	30	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Figure 5</u>	15 V		20	10	-	ns
		nMR HIGH;	5 V		80	40	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Figure 6</u>	15 V		24	12	-	ns
t _{rec}	recovery time	pin nMR;	5 V		50	20	-	ns
		see Figure 6	10 V		30	10	-	ns
			15 V		20	5	-	ns
f _{max}	maximum frequency	see Figure 5	5 V		7	15	-	MHz
			10 V		15	30	-	MHz
			15 V		22	44	-	MHz

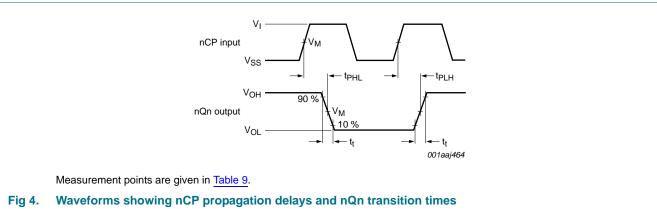
^[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

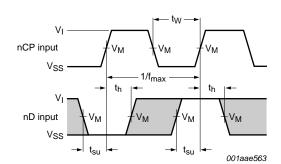
 P_D can be calculated from the formulas shown. $V_{SS} = 0 \text{ V}$; $t_r = t_f \le 20 \text{ ns}$; $T_{amb} = 25 \text{ }^{\circ}\text{C}$.

Symbol	Parameter	V_{DD}	Typical formula for P _D (μW)	where:
P_D	dynamic power	5 V	$P_D = 1500 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f _i = input frequency in MHz;
dissipation 1		10 V	$P_D = 6300 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f _o = output frequency in MHz;
		15 V	$P_D = 17000 \times f_i + \Sigma (f_0 \times C_L) \times V_{DD}^2$	C_L = output load capacitance in pF;
				V _{DD} = supply voltage in V;
				$\Sigma(C_L \times f_o)$ = sum of the outputs.

12. Waveforms



rig 4. Waveforms showing nor propagation delays and fight transition times



The shaded area indicates where the input is permitted to change for predictable output performance.

Set-up and hold times are shown as positive values but may be specified as negative values;

Measurement points are given in Table 9.

Fig 5. Waveforms showing set-up times, hold times, and minimum clock pulse width

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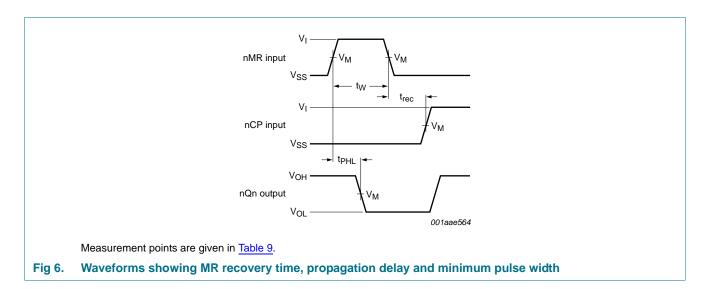
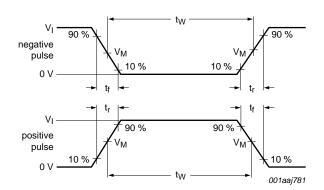


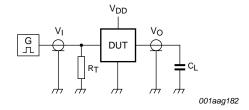
Table 9. Measurement points

Supply voltage	Input	Output
V_{DD}	V _M	V _M
5 V to 15 V	0.5V _{DD}	0.5V _{DD}

Dual 4-bit static shift register



a. Input waveforms



b. Test circuit

Test data is given in <u>Table 10</u>.

Definitions for test circuit:

DUT = Device Under Test;

C_L = load capacitance including jig and probe capacitance;

 $R_{T} = \mbox{termination} \ \mbox{resistance} \ \mbox{should} \ \mbox{be} \ \mbox{equal} \ \mbox{to} \ \mbox{the} \ \mbox{output} \ \mbox{impedance} \ \mbox{Z_{0} of the pulse} \ \mbox{generator}.$

Fig 7. Test circuit for measuring switching times

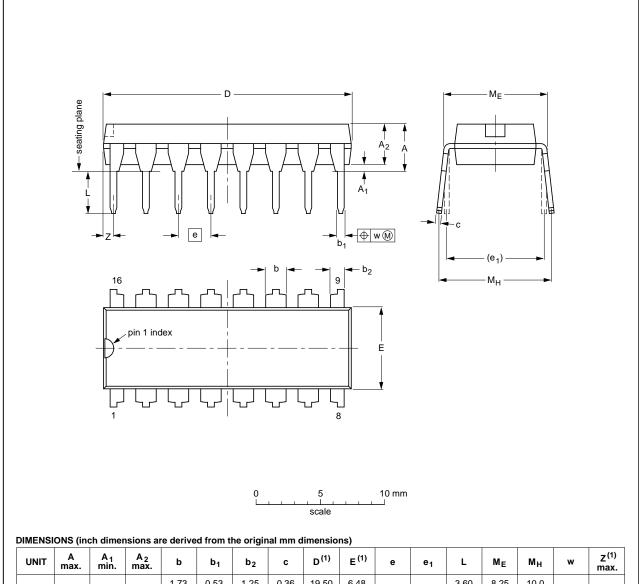
Table 10. Test data

Supply voltage	Input	Load	
V_{DD}	VI	t _r , t _f	CL
5 V to 15 V	V _{SS} or V _{DD}	≤ 20 ns	50 pF

13. Package outline

DIP16: plastic dual in-line package; 16 leads (300 mil)

SOT38-4



UNIT	A max.	A ₁ min.	A ₂ max.	b	b ₁	b ₂	С	D ⁽¹⁾	E ⁽¹⁾	е	e ₁	L	ME	Мн	w	Z ⁽¹⁾ max.
mm	4.2	0.51	3.2	1.73 1.30	0.53 0.38	1.25 0.85	0.36 0.23	19.50 18.55	6.48 6.20	2.54	7.62	3.60 3.05	8.25 7.80	10.0 8.3	0.254	0.76
inches	0.17	0.02	0.13	0.068 0.051	0.021 0.015	0.049 0.033	0.014 0.009	0.77 0.73	0.26 0.24	0.1	0.3	0.14 0.12	0.32 0.31	0.39 0.33	0.01	0.03

Note

1. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE			
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT38-4						95-01-14 03-02-13	

Fig 8. Package outline SOT38-4 (DIP16)

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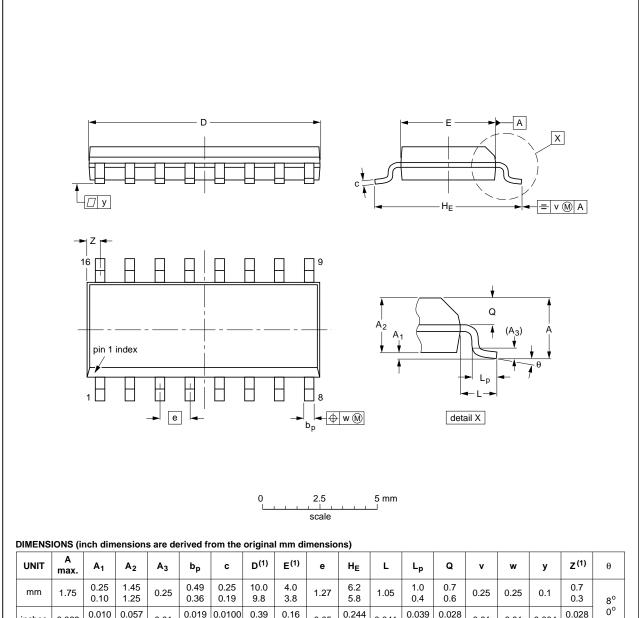
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SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E ⁽¹⁾	е	HE	L	Lp	Q	v	w	у	Z ⁽¹⁾	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	10.0 9.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01		0.0100 0.0075	0.39 0.38	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016		0.01	0.01	0.004	0.028 0.012	0°

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE			
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT109-1	076E07	MS-012				99-12-27 03-02-19	

Fig 9. Package outline SOT109-1 (SO16)

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14. Revision history

Table 11. Revision history

	-				
Document ID	Release date	Data sheet status	Change notice	Supersedes	
HEF4015B v.8	20111121	Product data sheet -		HEF4015B v.7	
Modifications:	 Legal page: 	s updated.			
	 Changes in 	"General description" and "I	eatures and benefits".		
HEF4015B v.7	20110914	Product data sheet	-	HEF4015B v.6	
HEF4015B v.6	20091103	Product data sheet	-	HEF4015B v.5	
HEF4015B v.5	20090624	Product data sheet	-	HEF4015B v.4	
HEF4015B v.4	20090127	Product data sheet	-	HEF4015B_CNV v.3	
HEF4015B_CNV v.3	19950101	Product specification	-	HEF4015B_CNV v.2	
HEF4015B_CNV v.2	19950101	Product specification	-	-	

Dual 4-bit static shift register

15. Legal information

15.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
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